

6 WQW

US117 P47 GUN 19708

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Notes on the Board

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The output of the voltage regulator drives a potential divider consisting of the tuning pot, and from this a voltage divider (V<sub>ref</sub>) is used, gain, non-inverting power op-amp buffer provides sufficient output impedance capability to drive the Gunn diode, which contains internal shot circuit protection. Protection for the Gunn diode from overvoltage is provided by a zener diode, this will handle changing of the positive output voltage or increased.

PTC and modulator are also applied to the power supply by adding a reference line. The mid output of the 100:1000 is buffered by op-amp operating in non-inverting and non-inverting unity gain modes. The 100:1000 PTC operation with the local oscillator on either side of the mixer signal. The PTC sense is selected by means of a center-off toggle switch - in the center position the 100:1000 is off, otherwise normal operation. The tuning range does vary slightly with different HFU modes selected, however, this is not really a problem. Once used, PTC network additive once a signal - even one quite weak to the noise - is captured it will remain steady within the bandwidth, quite happily for hours and will unless the network is disturbed. By connecting a current meter in series with a suitable resistor across the two PTC outputs, a tuning meter may be used.

A centre off switch also selects the additional sources both tone and speech tones are available. The tone source is a simple Wien-bridge phase shift oscillator operating at around 10kHz, whilst the microphone excitation is a dedicated 100:1000 microphone PTC. The use of PTC makes it very difficult indeed to expandable, even when standing on a hilltop in the middle of a gale (using the microwave path). Separate adjustment adjustments are provided for each source.

The received intermediate frequency is set 10.70MHz. This has been chosen for several reasons. Although it does, we must have some minor disadvantages. The major reasons for using 10.7MHz are concerned with elimination of the need to automatically tune the oscillator or to use a separate transmitter which could be better i.f.'s are employed, availability, ease of generating good i.f. for audio as a reasonable cost, impedance, compatibility for full duplex operation, and low losses associated with cable runs should the microphone head be operated remotely. The major disadvantage with the use of such a low i.f. frequency in microwave terms are concerned with the generation of noise signals by the Gunn oscillator. HF oscillators generate noise with the carrier, one would expect a function both of the device and the circuitry surrounding it. The noise sidebands generated can be thought of as being the original, therefore due to amplitude modulation of the oscillator (a) both noise generated within the device and external to it) and by the phase modulation which happens whenever an oscillator is amplitude modulated. In the case of simple systems such as typical amateur 100Hz equipment, the main problem comes from the amplitude noise component, as the phase noise components are cancelled at the mixer. In modern Gunn diode transmitters those intended for doppler radar (or hunter/killer) use, the problems are not at all serious and can usually be completely forgotten.

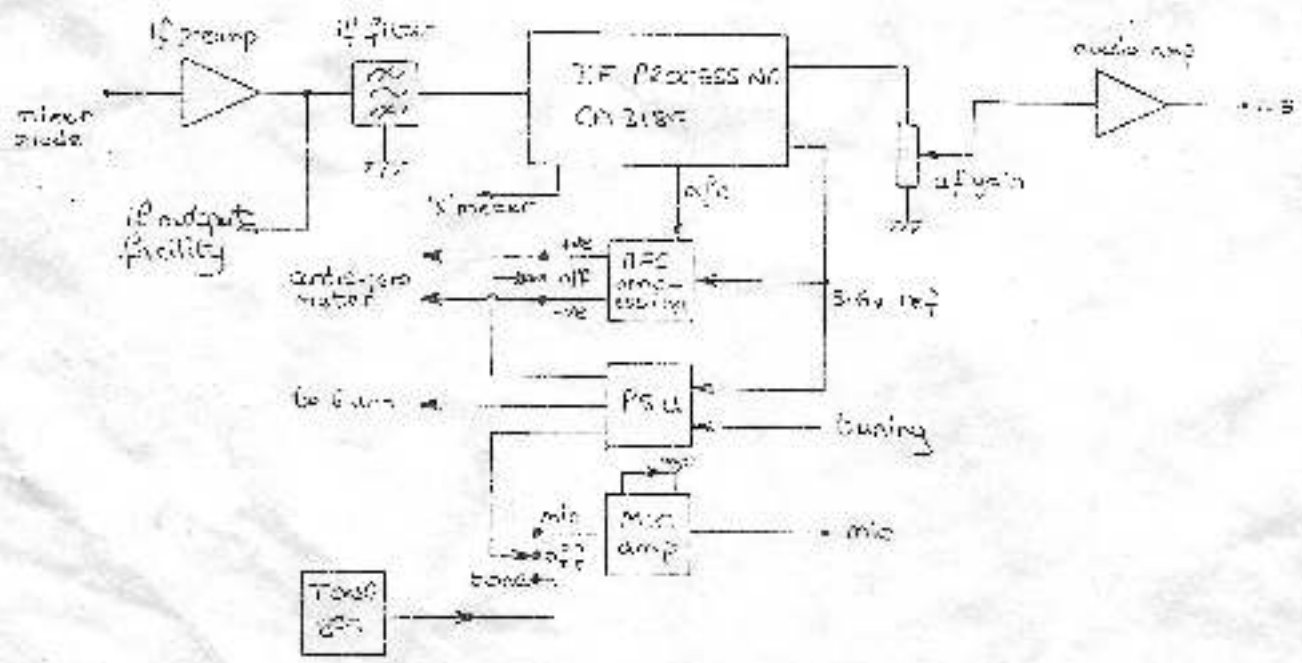
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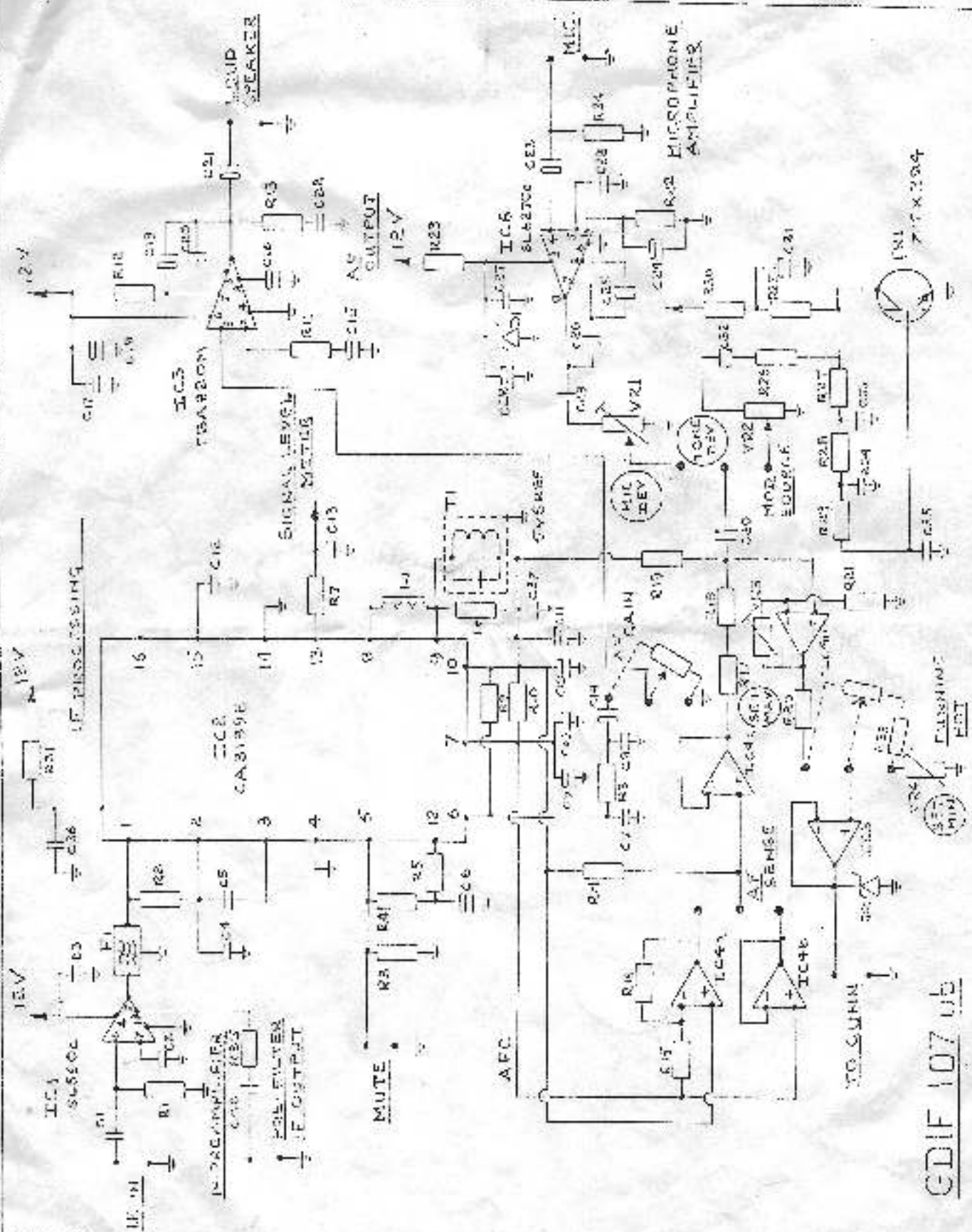
A schematic of the system is shown in the block diagram. This includes a pre-amplifier, an IF amplifier, an IF processor, an audio amplifier, and a speaker. The pre-amplifier is a 100k resistor network. The IF amplifier is a 100k resistor network. The IF processor is a 100k resistor network. The audio amplifier is a 100k resistor network. The speaker is a 100k resistor network.

Following the audio amplifier, the signal is processed by the processor defined in the block diagram. The processor is a 100k resistor network. The processor is a 100k resistor network. The processor is a 100k resistor network. The processor is a 100k resistor network. The processor is a 100k resistor network.

The audio output stage is a 100k resistor network. The audio output stage is a 100k resistor network. The audio output stage is a 100k resistor network. The audio output stage is a 100k resistor network. The audio output stage is a 100k resistor network.

Block Diagram





ROIF 1975 Component Schedule

R4	10K	C1-5	100	101	OLECOE
R5	33K	C6	242	102	000189e
R6	100K	C7	100	103	TIFF22e
R7	20K	C8	110	104	TLCEA
R8	470K	C9-10	100	105	UP 759
R9	50K	C11-12	100	106	SLC200
R10	10K	C13	242		
R11	242	C14	100		
R12	4K	C15-16	100	11	200K
R13	4K7	C17	100	11	10004528F
R14	100K	C18	100		
R15	100K	C19	100	11	010110.7
R16	540	C20	100		
R17	100	C21	100		
R18	33K	C22	100		
R19	30K	C23	100		
R20	100	C24	100		
R21	100K	C25-26	100		
R22	33K	C27	100		
R23	100	C28	242		
R24	100K	C29	100		
R25	100K	C30	100		
R26	100K	C31	100		
R27	100K	C32	100		
R28	100K	C33-34	100		
R29	100K	C35	100		
R30	100K	C36	100		
R31	100K	C37	100		
R32	100K	C38-39	100		
R33	100K				
R34	100K				
R35	100K				
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R98	100K				
R99	100K				
R100	100K				

## Building a system.

Integrating the GDF 1004 with the rest of your 10GHz system isn't a difficult job, however, if you spend a little time thinking about what you want to achieve, it will make life simpler still! Most people will want to use the board in conjunction with a surplus doppler module to operate over long line-of-sight paths. In this case the choice of the doppler module is very important; the most successful modules for this purpose being based upon a "throughline" design in which the oscillator is coupled to the mixer through an iris. Other units in which the oscillator and mixer are mounted side-by-side on the waveguide can be used, however, these are not really capable of the performance of the throughline units, particularly when used with a reasonably large antenna, as the physical offset causes significant differences in the radiation pattern. Nevertheless, this is still possibly a convenient way of making simple low performance systems for short distance line-of-sight links. If you want the highest performance, the GDF670000 design for a throughline mixer which appeared in *Radcom*, June 1979 can be thoroughly recommended. This can be built with hand tools and is not too difficult to set-up. Even with small waveguides such as the 1003 horns frequently found on surplus alarm modules it should be possible to cover line-of-sight paths of around 10km between two identical modules. It is even possible to cover a few km using just the open end of the waveguide as an internal directional antenna, such as 18" dishes, a pair of units will be able to cover space paths of several hundred kilometres as well as some constrained paths. We've listed some references at the end of this note which will help with designs for external components and with system analysis.

## Putting it in a box.

The connections to the board needed to get your system running are detailed in Fig.2. The timing and signal level meters are optional and can be omitted if not required. Likewise, the auto can be disabled by shorting the "mode" terminal pin to ground. The AFO and modulation select switches are centre-off toggle switches, although they could be replaced by rotary switches if desired. The main tuning control is preferably a ten-turn 1k linear law potentiometer. If this is not available, then a conventional 20 degree pot, with slow-motion drive could be used. A 10k log pot. is suitable as the 2k main control; if a control fitted with internal switch is available, then this can be used for on/off switching. Note that no reverse polarity protection is added to the board. This is best fitted to the power input socket. As the output impedance of typical mixer diodes is of the order of 200-400 ohms and the source impedance required by the amplifier for minimum noise figure is around 70 ohms some matching is required. A 4:1 (impedance) broadband transformer is suitable; the red winding is low impedance

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 whilst the green side is high impedance. By decoupling the 'cold' end of the transformer, the diode current can be easily measured. The microphone amplifier is intended for use with low impedance (200 ohm) ceramic microphones. NOTE THAT IT IS PROHIBITIVE TO SHORT THE AUDIO OUTPUT I.C. IF ITS OUTPUT IS SHORT CIRCUITED.

It is a good idea to mount the microwave board in a box and cover to surround it with polystyrene foam. A diecast box large enough to house the electronics as well as possibly a good idea, as any chance of r.f. breakthrough will be minimised.

#### Setting-up.

The setting up procedure breaks down into two phases: getting the oscillator onto frequency and then setting up the tuning, range and deviation controls. Before connecting the Gunn, turn the v.c. and modulation switches to their 'OFF' positions. Connect a voltmeter between pins 19 and 20. Turn the tuning pot. fully clockwise and adjust VFB for 0V output. Now turn the tuning pot. fully counter-clockwise and adjust VR4 for 0V output. If these adjustments are not straightforward, the tuning pot is probably connected the wrong way round. Once the power supply is secure, and position of the tuning pot. varies the output voltage smoothly from 6 to 18.0V. Set the output voltage to 7.5V. Switch off, and connect the Gunn oscillator - making sure that the polarity is correct. If the oscillator has been designed for positive ground operation, it will be necessary to carefully remove the Gunn diode and reverse it (the other way round). In a low-power diode, this will not cause any damage, however, care should be taken with heat-sinking of high power diodes. Connect the Gunn oscillator to the power supply and with the aid of a suitable instrument, adjust the mechanical tuning control to a frequency of oscillation at the centre of the band desired. (This will usually now be 10085MHz.) Now set the tuning control to maximum output and carefully adjust VR2 for the highest frequency available. It will usually be found that the output tuning characteristic (flatness-of) rather severely at this point, the maximum voltage should be adjusted to just prior to this.

Once the maximum frequency has been set, turn the tuning pot. fully counter-clockwise and adjust VR4 to the point where the output power just begins to fall steeply. This is the lowest frequency point at which the Gunn oscillator will oscillate reliably. Now measure the total tuning range and if necessary, adjust the mechanical tuning to centre the tuning range around the required frequency. Once the tuning range has been set, it should remain reasonably stable. It should only be necessary to adjust the mechanical tuning slightly if the load which the oscillator sees is changed significantly.

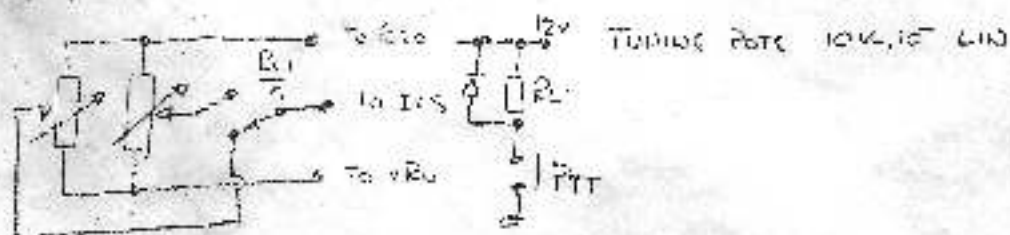
The simplest way to set the deviation controls is to get reports from another station, however, if another source of unmodulated 100MHz is available, the facility exists to set these controls using the receiving circuitry already on the board. Tune in the source and monitor the audio output.

of the GDF 107ub, then slowly adjust the tone and speech levels until they sound right. Distortion can be reduced with this job.

Other notes:

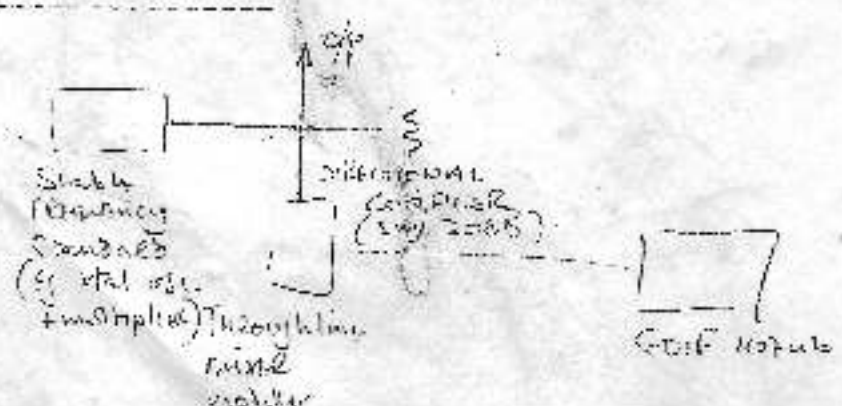
The GDF 107k can be used in applications other than that of a simple duplex transceiver. One of the significant extensions is to allow operation as a single frequency (simplex) transceiver. It is possible to do this really quite simply. By relay switching the outputs of two different tuning pots from a push-to-talk line, independent tuning of the transmit and receive frequencies is easily achieved.

Independent +/- switching.



Because the GDF 107ub has excellent performance, one application is to frequency lock a Gunn oscillator to a stable source. This has several applications: it can be used for frequency to stabilize the frequency of a auto-tune beacon transmitter, or to generate a local oscillator capable of sufficient stability to allow the use of noise with its consequent system performance gain. It is unfortunately not possible to obtain a sufficiently narrow spectral line to allow the use of noise or conventional modes. (Most of the energy is, however, still contained within a 1kHz bandwidth) although the system bandwidth can be reduced by accepting that there will be no normal noise to a signal and taking what sounds like an incredibly rough normal signal or an sso condition. Keying is best accomplished by frequency shift keying the crystal controlled performance. If the GDF 107ub is to be used in just a frequency locking application, then there is some advantage in increasing the loss bandwidth by reducing the value of Q. Some experimentation may be required here.

Frequency locking



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Useful references and further readings.

Radio Communications

Jul. 1984	p393	Basic transceiver systems
Jan. 1981	p47	Fixed ops. using passive reflectors
Mar. 1981	p21	Field Plotting
Feb. 1981	p147	QRPF Signaling Course
Mar. 1980	p177	Trpo operation
Apr. 1980	p332	Trpo openings
Oct. 1980	p399	Calculating bearings and distances from National Grid references
Nov. 1980	p106	Aligning antennas accurately
Nov. 1979	p394	Propagation enhancements
Feb. 1978	p17	Microwaves with checking
May 1977	p133	Performance of equipment over land of sight paths
Jun. 1977	p492	Throughline 10GHz Transducer
Oct. 1978	p307	Superrefraction
Nov. 1970	p95	Superrefraction
Jul. 1977	p453	Superrefraction
Feb. 1976	p123	QRPFF Gunn oscillation
Mar. 1976	p191	Duskin like as dish
Mar. 1976	p352	Direct controlled frequency planar
Oct. 1976	p737	Simple dish feed
Feb. 1976	p125	Self calibrating wavemeter
Oct. 1975	p261	High Q wave meter
Oct. 1975	p612	(Directional) Coupled wave transmitter
Nov. 1972	p61	Wave antenna design
Apr. 1972	p259	Loop antenna design

Practical Handbooks

June, July, and August 1981. The QRP "Box" Microwave transceiver.

The Microwave Society. Data pack.

The RSGB VHF/UHF Manual contains many useful items.

Enjoy your microwaving!

